#### MLQ 2021

# Improving Quantum Sensing with Variational Methods

**JOHANNES JAKOB MEYER, FU BERLIN & QMATH** 



#### arxiv:2006.06303

#### A variational toolbox for quantum multi-parameter estimation

Johannes Jakob Meyer, 1 Johannes Borregaard, 2,3 and Jens Eisert 1

<sup>1</sup>Dahlem Center for Complex Quantum Systems, Freie Universität Berlin, 14195 Berlin, Germany
<sup>2</sup>Qutech and Kavli Institute of Nanoscience, Delft University of Technology, 2628 CJ Delft, The Netherlands
<sup>3</sup>Mathematical Sciences, Universitetsparken 5, 2100 København Ø, Matematik E, Denmark

(Dated: June 11, 2020)



Johannes Borregaard TU Delft



Jens Eisert FU Berlin



Physical quantities (magnetic fields, energies, ...) need to be **measured** accurately

Physical quantities (magnetic fields, energies, ...) need to be **measured** accurately



noun

the scientific study of measurement.

Physical quantities (magnetic fields, energies, ...) need to be **measured** accurately
Study how **quantum effects** can help



noun

the scientific study of measurement.

Physical quantities (magnetic fields, energies, ...) need to be **measured** accurately
Study how **quantum effects** can help



noun

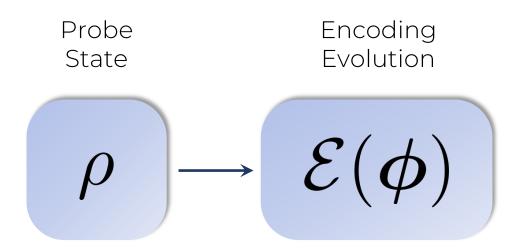
the scientific study of measurement.

Probe State



Physical quantities (magnetic fields, energies, ...) need to be **measured** accurately
Study how **quantum effects** can help



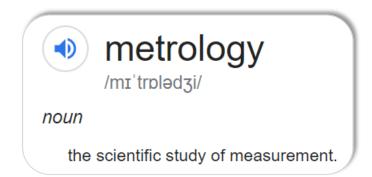


Physical quantities (magnetic fields, energies, ...) need to be **measured** accurately
Study how **quantum effects** can help



Probe State Encoding Evolution Measurement 
$$ho \longrightarrow \mathcal{E}(\phi) \longrightarrow \mathcal{M}$$

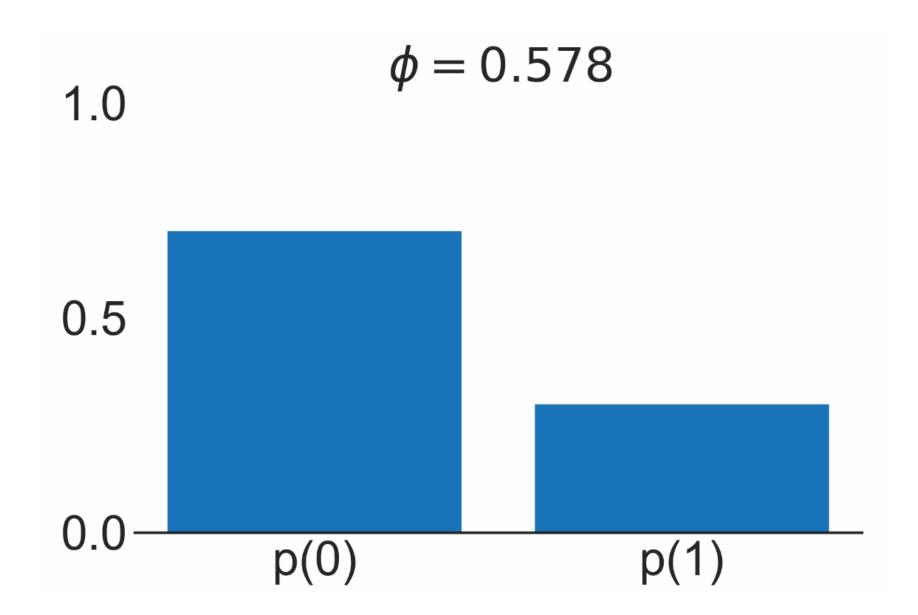
Physical quantities (magnetic fields, energies, ...) need to be **measured** accurately
Study how **quantum effects** can help



Probe State Encoding Evolution Measurement Output Distribution 
$$ho \longrightarrow \mathcal{E}(\phi) \longrightarrow \mathcal{M} \longrightarrow p_l(\phi)$$

# Gathering Intuition

# Gathering Intuition



Task: Compute an **estimator** from the output distribution

$$p_l(\boldsymbol{\phi}) \rightarrow \hat{\boldsymbol{\varphi}} \colon \mathbb{E}\{\hat{\boldsymbol{\varphi}}\} = \boldsymbol{\phi}$$

Task: Compute an **estimator** from the output distribution

$$p_l(\boldsymbol{\phi}) \rightarrow \hat{\boldsymbol{\varphi}} : \mathbb{E}\{\hat{\boldsymbol{\varphi}}\} = \boldsymbol{\phi}$$

Precision from n samples is limited by Cramér-Rao bound

$$\operatorname{Cov}(\hat{\boldsymbol{\varphi}}) \ge \frac{1}{n} I_{\boldsymbol{\phi}}^{-1}(\mathcal{M})$$

Task: Compute an **estimator** from the output distribution

$$p_l(\boldsymbol{\phi}) \rightarrow \hat{\boldsymbol{\varphi}} : \mathbb{E}\{\hat{\boldsymbol{\varphi}}\} = \boldsymbol{\phi}$$

Precision from n samples is limited by Cramér-Rao bound

$$\operatorname{Cov}(\hat{\boldsymbol{\varphi}}) \ge \frac{1}{n} I_{\boldsymbol{\phi}}^{-1}(\mathcal{M})$$

$$\operatorname{Tr}\{\operatorname{Cov}(\hat{\boldsymbol{\varphi}})\} = \operatorname{MSE}(\hat{\boldsymbol{\varphi}})$$

Task: Compute an **estimator** from the output distribution

$$p_l(\boldsymbol{\phi}) \rightarrow \hat{\boldsymbol{\varphi}} : \mathbb{E}\{\hat{\boldsymbol{\varphi}}\} = \boldsymbol{\phi}$$

Precision from n samples is limited by Cramér-Rao bound

$$\operatorname{Cov}(\hat{\boldsymbol{\varphi}}) \ge \frac{1}{n} I_{\boldsymbol{\phi}}^{-1}(\mathcal{M}) \ge \frac{1}{n} \mathcal{F}_{\boldsymbol{\phi}}^{-1}$$

Sensing amounts to estimating the underlying physical parameters from a classical probability distribution

Sensing amounts to estimating the underlying physical parameters from a classical probability distribution

Estimation precision is limited by the Cramér-Rao bound

Sensing amounts to estimating the underlying physical parameters from a classical probability distribution

Estimation precision is limited by the Cramér-Rao bound

Attainble precision is quantified by the classical Fisher information

Sensing amounts to estimating the underlying physical parameters from a classical probability distribution

Estimation precision is limited by the Cramér-Rao bound

Attainble precision is quantified by the classical Fisher information

The quantum Fisher information bounds the attainable Fisher information

Sensing amounts to estimating the underlying physical parameters from a classical probability distribution

Estimation precision is limited by the Cramér-Rao bound

Attainble precision is quantified by the classical Fisher information

The quantum Fisher information bounds the attainable Fisher information

→ Classical Fisher information should be used to judge sensing quality!

We need to find optimal probes and measurements

We need to find optimal probes and measurements

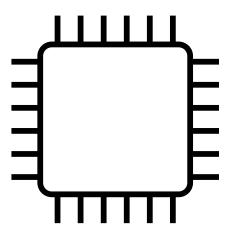
Complicated under noise and device limitations

We need to find optimal probes and measurements

Complicated under noise and device limitations

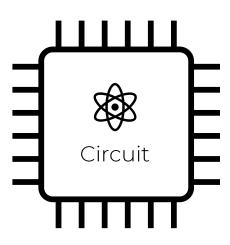
We need to find optimal probes and measurements

Complicated under noise and device limitations



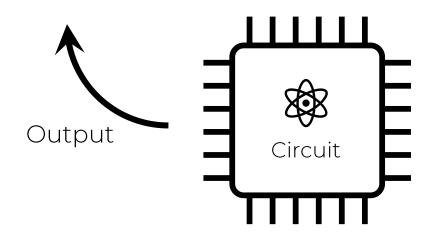
We need to find optimal probes and measurements

Complicated under noise and device limitations



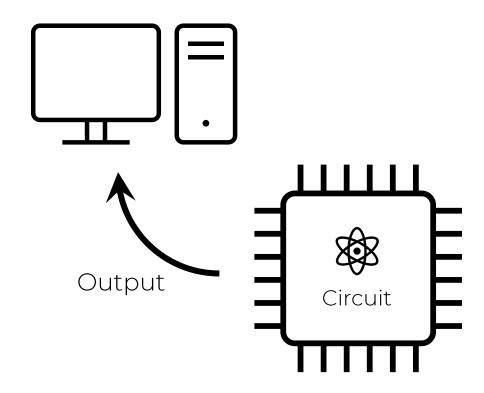
We need to find optimal probes and measurements

Complicated under noise and device limitations



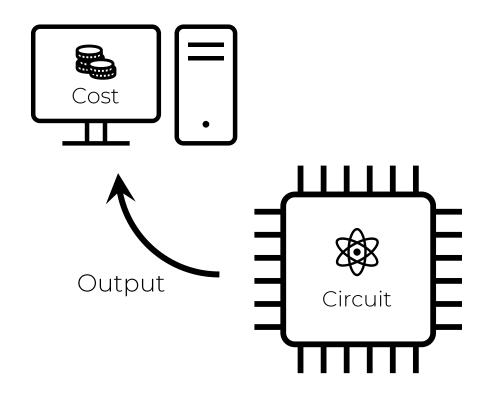
We need to find optimal probes and measurements

Complicated under noise and device limitations



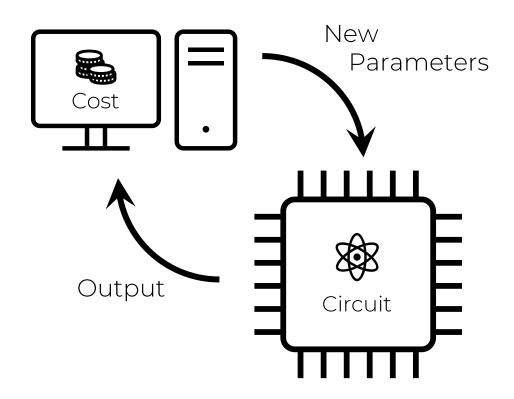
We need to find optimal probes and measurements

Complicated under noise and device limitations



We need to find optimal probes and measurements

Complicated under noise and device limitations

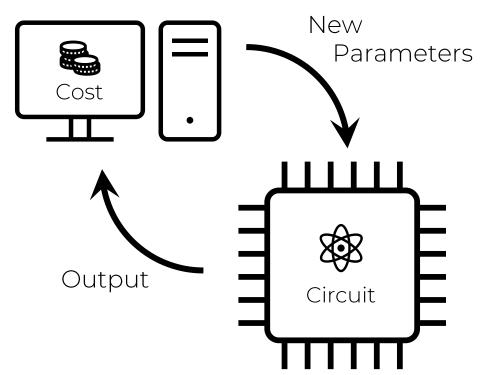


We need to find optimal probes and measurements

Complicated under noise and device limitations

NISQ techniques come to the rescue: use variational approaches

Prior work<sup>1,2</sup> focused on single-parameter metrology and surrogates for the Quantum Fisher Information



#### Cost Function

#### Cost Function

Include post-processing by considering a function of the parameters: Exploit transformation rule of Fisher Information Matrix

#### Cost Function

Include post-processing by considering a function of the parameters: Exploit transformation rule of Fisher Information Matrix

$$f = f(\phi) \rightarrow I_f = J^T I_{\phi} J$$

#### Cost Function

Include post-processing by considering a function of the parameters: Exploit transformation rule of Fisher Information Matrix

$$f = f(\phi) \rightarrow I_f = J^T I_{\phi} J$$

Need a scalar cost function: Apply weighted trace to both sides of the CRB!

#### Cost Function

Include post-processing by considering a function of the parameters: Exploit transformation rule of Fisher Information Matrix

$$f = f(\phi) \rightarrow I_f = J^T I_{\phi} J$$

Need a scalar cost function: Apply weighted trace to both sides of the CRB!

$$\operatorname{Tr}\{W\operatorname{Cov}(\hat{\boldsymbol{f}})\} \ge \frac{1}{n}\operatorname{Tr}\{WI_{\boldsymbol{f}}^{-1}\} = \frac{1}{n}C_W$$

#### Calculation of Fisher Information

#### Calculation of Fisher Information

Fisher Information Matrix w.r.t. the physical parameters

$$[I_{\phi}]_{jk} = \sum_{l} \frac{1}{p_{l}} \frac{\partial p_{l}}{\partial \phi_{j}} \frac{\partial p_{l}}{\partial \phi_{k}}$$

#### Calculation of Fisher Information

Fisher Information Matrix w.r.t. the physical parameters

$$[I_{\phi}]_{jk} = \sum_{l} \frac{1}{p_{l}} \frac{\partial p_{l}}{\partial \phi_{j}} \frac{\partial p_{l}}{\partial \phi_{k}}$$

Exploit parameter-shift rule<sup>1,2</sup> to calculate derivatives

$$\partial_j p_l(\boldsymbol{\phi}) = \frac{1}{2} \left[ p_l \left( \boldsymbol{\phi} + \frac{\pi}{2} \boldsymbol{e}_j \right) - p_l \left( \boldsymbol{\phi} - \frac{\pi}{2} \boldsymbol{e}_j \right) \right]$$

The classical Fisher information matrix is calculated from the output probabilities and their derivatives w.r.t. the physical parameters

The classical Fisher information matrix is calculated from the output probabilities and their derivatives w.r.t. the physical parameters

The derivatives can be calculated on the device via the parameter-shift rule

The classical Fisher information matrix is calculated from the output probabilities and their derivatives w.r.t. the physical parameters

The derivatives can be calculated on the device via the parameter-shift rule

The classical Fisher information matrix w.r.t. post-processed parameters can be computed using the post-processing's Jacobian

The classical Fisher information matrix is calculated from the output probabilities and their derivatives w.r.t. the physical parameters

The derivatives can be calculated on the device via the parameter-shift rule

The classical Fisher information matrix w.r.t. post-processed parameters can be computed using the post-processing's Jacobian

The cost function is obtained from a weighted trace of the Cramér-Rao bound

Multiple extensions of the algorithm, for example including prior knowlege (Bayesian approach)

Multiple extensions of the algorithm, for example including prior knowlege (Bayesian approach)

A parameter-shift rule for noise channels

Multiple extensions of the algorithm, for example including prior knowlege (Bayesian approach)

A parameter-shift rule for noise channels

Details on the implementation of parameter-shift rules in experiments

Multiple extensions of the algorithm, for example including prior knowlege (Bayesian approach)

A parameter-shift rule for noise channels

Details on the implementation of parameter-shift rules in experiments

Numerical experiments that showcase the performance of the approach

Take-Home Message

Variational methods on near-term quantum computers can be used to improve quantum sensors

# Thank you for your attention!



Paper



Demo



Slides









Single Parameter Multiparameter

Kaubrügger et al.

COST FUNCTION

Spin Squeezing

STATE PREPARATION

Fixed Circuit

MEASUREMENT

Fixed



Kaubrügger et al.

COST FUNCTION

Spin Squeezing

STATE PREPARATION

Fixed Circuit

MEASUREMENT

Fixed

Koczor et al.

COST FUNCTION

Fidelity

STATE PREPARATION

Parametrized Circuit

MEASUREMENT

Single Parameter Multiparameter

Kaubrügger et al.

COST FUNCTION

Spin Squeezing

STATE PREPARATION

Fixed Circuit

MEASUREMENT

Fixed

Ours

COST FUNCTION

Classical Fisher Info

STATE PREPARATION

Parametrized Circuit

MEASUREMENT

Parametrized Circuit

Koczor et al.

COST FUNCTION

Fidelity

STATE PREPARATION

Parametrized Circuit

MEASUREMENT

Single Parameter Multiparameter

Kaubrügger et al.

COST FUNCTION

Spin Squeezing

STATE PREPARATION

Fixed Circuit

MEASUREMENT

Fixed

Ours

COST FUNCTION

Classical Fisher Info

STATE PREPARATION

Parametrized Circuit

MEASUREMENT

Parametrized Circuit

Koczor et al.

COST FUNCTION

Fidelity

STATE PREPARATION

Parametrized Circuit

MEASUREMENT

N/A

Yang et al.

COST FUNCTION

Purity Loss

STATE PREPARATION

Control Sequence

MEASUREMENT

Single Parameter Multiparameter

Kaubrügger et al.

COST FUNCTION

Spin Squeezing

STATE PREPARATION

Fixed Circuit

MEASUREMENT

Fixed

Ours

COST FUNCTION

Classical Fisher Info

STATE PREPARATION

Parametrized Circuit

MEASUREMENT

Parametrized Circuit

Ma et al.

COST FUNCTION

Classical Fisher Info

STATE PREPARATION

Optimized Circuit

MEASUREMENT

Optimized Circuit

Koczor et al.

COST FUNCTION

Fidelity

STATE PREPARATION

Parametrized Circuit

MEASUREMENT

N/A

Yang et al.

COST FUNCTION

Purity Loss

STATE PREPARATION

Control Sequence

MEASUREMENT

Single Parameter Multiparameter

Kaubrügger et al.

COST FUNCTION

Spin Squeezing

STATE PREPARATION

Fixed Circuit

MEASUREMENT

Fixed

Ours

COST FUNCTION

Classical Fisher Info

STATE PREPARATION

Parametrized Circuit

MEASUREMENT

Parametrized Circuit

Ma et al.

COST FUNCTION

Classical Fisher Info

STATE PREPARATION

Optimized Circuit

MEASUREMENT

Optimized Circuit

Koczor et al.

COST FUNCTION

Fidelity

STATE PREPARATION

Parametrized Circuit

MEASUREMENT

N/A

Yang et al.

COST FUNCTION

Purity Loss

STATE PREPARATION

Control Sequence

MEASUREMENT

N/A

Beckey et al.

COST FUNCTION

Quantum Fisher Bounds

STATE PREPARATION

Arbitrary Circuit

MEASUREMENT